

Errata
Nicholson, *Elementary Linear Algebra*, 1st Edition

Each of the following points represents how the text should appear, and are listed by page number as well as by question, example, line number, or other indicator.

Page 71

Example 2:

Example 2. *Given elementary matrices*

$$E_1 = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix},$$

write down the inverses.

Page 84

Exercises, Question #1:

1. In each case use the given LU-factorization of A to solve the system $AX = B$ by solving $LY = B$ and $UX = Y$ by backward and forward substitution respectively.

Page 86

Question #12(b):

- (b) Show that the factorization in (a) is unique if A is invertible.

Page 118

Question #16(b):

(b)
$$\begin{bmatrix} A & 0 & 0 \\ X & B & 0 \\ Z & Y & C \end{bmatrix}$$

Page 120
Lines 28-31

Using this we can compute A^3 as follows:

$$A^3 = AA^2 = (PDP^{-1})(PD^2P^{-1}) = PD^3P^{-1}.$$

Continuing in this way (and noting that this works even if D is not diagonal), we obtain

Page 137
Footnote #8

⁸Suppose λ_1 and λ_2 are both dominant (possibly equal), that is $|\lambda_1| = |\lambda_2| > |\lambda_i|$ for each $i \geq 3$. Then $V_k \approx \lambda_1^k b_1 X_1 + \lambda_2^k b_2 X_2$ for sufficiently large k . A similar analysis applies if λ_1, λ_2 and λ_3 are all dominant.

Page 146
Question #5(f):

(f) From that point on, the hawk survival rate drops to 0.50. The biologists are alarmed that this may wipe out the hawk population. Test to see what the model is predicting, and explain what is happening.

Page 161
Question #20:

20. Express each of the following in polar form.

- | | |
|---------------------|----------------------|
| (a) $2 - 2i$ | (b) $-2i$ |
| (c) $-\sqrt{3} + i$ | (d) $-3 - \sqrt{3}i$ |
| (e) $5i$ | (f) $5(1 + i)$ |

Page 167

Question #14:

[Questions 14(c) and 14(d) have been removed.]

Page 205

3.3.1 Position Vectors, Line 3

$$\vec{p} = \overline{OP} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = [x \ y \ z]^T.$$

Page 206

Line 6

the position vector $\vec{p} = [x \ y \ z]^T$ of P , and read off its *components* x , y , and

Page 246

Question #16(d):

(d) Y -Expansion by 2, followed by the rotation through $\pi/2$.

Page 261

Independence Test, Step 2.

Step 2. Show that the only way this can happen is the trivial one with all coefficients $t_i = 0$.

Page 276

Exercises, Question #3(c)

(c) $\{[-4 \ 3 \ -2]^T, [-1 \ 1 \ 11]^T, [-3 \ 2 \ -9]^T\}$ in \mathbb{R}^3 .

Page 278

Question #15(a):

15. (a) Find a basis of vectors in \mathbb{R}^3 consisting of vectors whose components sum to 1.

Page 279

Question #25:

25. Let U and W be any two subspaces of \mathbb{R}^n , and consider the subspaces

$$U \cap W = \{X \text{ in } \mathbb{R}^n \mid X \text{ is in both } U \text{ and } W\}$$

$$U + W = \{X \text{ in } \mathbb{R}^n \mid X \text{ is a sum of a vector in } U \text{ and a vector in } W\}$$

As in Exercise 23 §4.1. Show that $\dim(U + W) = \dim U + \dim W - \dim(U \cap W)$.

[Hint: Let $\{X_1, \dots, X_d\}$ be a basis of $U \cap W$, and by Theorem 3, extend it to bases

$\{X_1, \dots, X_d, Y_1, \dots, Y_k\}$ and $\{X_1, \dots, X_d, Z_1, \dots, Z_m\}$ of U and W respectively.

Show that $\{X_1, \dots, X_d, Y_1, \dots, Y_k, Z_1, \dots, Z_m\}$ is a basis of $U + W$.]

Page 284

Theorem 3, Point (4)

- (4) $A^T A$ is an invertible $n \times n$ matrix.

Page 285

Lines 1-3

that $X = 0$. So assume that $(A^T A)X = 0$. Write $AX = [y_1 \ y_2 \ \dots \ y_m]^T$ and compute

$$y_1^2 + y_2^2 + \dots + y_m^2 = (AX)^T (AX) = (X^T A^T)AX = X^T (A^T AX) = X^T 0 = 0.$$

Page 285

Theorem 3, Point (4)

- (4) AA^T is an invertible $m \times m$ matrix.

Page 288

Question #3(a)-(c):

(a) $\text{row}A = \text{span}\{[1 \ 0 \ 0 \ 1], [0 \ 1 \ 1 \ 0], [0 \ 0 \ 0 \ 1]\}$.

(b) $\text{row}A = \text{span}\{[1 \ 2 \ -1 \ 3], [2 \ -3 \ 1 \ 4], [4 \ -13 \ 5 \ 6]\}$.

(c) $\text{row}A = \text{span}\{[-1 \ 0 \ 3 \ 2], [3 \ 2 \ 0 \ -4], [9 \ 8 \ 9 \ -10], [4 \ 2 \ -3 \ -6]\}$.

Page 288

Question #4(c):

(c) $U = \text{span}\{[-1 \ 0 \ 3 \ 2]^T, [3 \ 2 \ 0 \ -4]^T, [9 \ 8 \ 9 \ -10]^T, [4 \ 2 \ -3 \ -6]^T\}$

Page 302

Solution, Line 1:

Solution. The columns of A are $C_1 = [1 \ -1 \ 0 \ 0]^T$, $C_2 = [1 \ 0 \ 1 \ 0]^T$ and

Page 321

Final line:

then use (c) and Theorem 4 §4.3.]

Page 334

Question #14, Line 3

$D = \text{diag}(\lambda_1, \dots, \lambda_n)$ where $P^{-1} = P^T$ and each $\lambda_i \geq 0$, take $B =$

Page 350

Exercises, Question #1(c):

(c) Every symmetric matrix with positive determinant is positive definite.

Page 352

Question #12:

12. If A is an $n \times n$ positive definite matrix, and if U is an $n \times m$ matrix of rank m , show that $U^T A U$ is positive definite [Hint: Theorem 3 §4.4.]

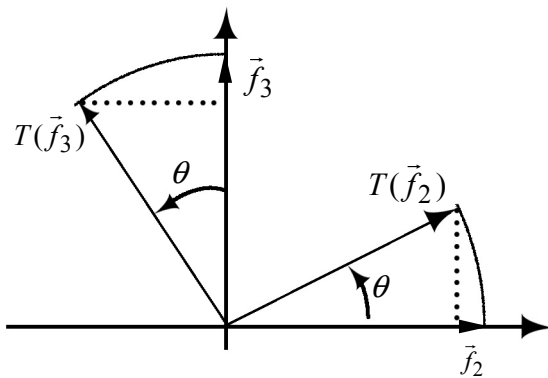
Page 358

7th-to-final line:

is uniquely determined *if it exists*. The natural temptation is to *define* T by

Page 365

Diagram #2:



Page 373

Question #6(b):

- (b) Find $T([x_1 \ x_2 \ x_3 \ x_4]^T)$ if $T: \mathbb{R}^4 \rightarrow \mathbb{R}^2$ is a linear transformation satisfying $T([1 \ 1 \ 0 \ 0]^T) = [2 \ -1]^T$, $T([0 \ 1 \ 0 \ 0]^T) = [-2 \ 3]^T$, $T([0 \ 1 \ 0 \ 2]^T) = [1 \ 0]^T$ and $T([0 \ 0 \ 1 \ 0]^T) = [0 \ -1]^T$.

Page 374

Question #17, Line 1:

Show that the composite of two distance preserving transformations of \mathbb{R}^n

Page 387

Question #24(a):

24. (a) Show that $\det \bar{Z} = \overline{\det Z}$ for every $n \times n$ complex matrix Z . [Hint: Use induction on n and apply the Laplace expansion.]

Page 397

Question #18(a):

18. (a) If X is an eigenvector of B corresponding to λ_i , show that $R(X) = \lambda_i$.

Page 412

Question #24(a):

24. (a) Show that $\mathbb{M}_{2,2} = \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\}$.

Page 423

Question #31:

31. Show that $\mathbb{F}[0,1]$ is infinite dimensional.

Page 424

Question #35(c)-(d):

(c) If U and W are both finite dimensional, show that $U + W$ is also finite dimensional (even though V may not be finite dimensional). [Hint: If C and D are (finite) bases of U and W respectively show that $C \cup D = \{\mathbf{v} \text{ in } V \mid \mathbf{v} \text{ is in } C \text{ or } \mathbf{v} \text{ is in } D\}$ spans $U + W$.]

(d) If V is finite dimensional, show that $\dim(U + W) = \dim U + \dim W - \dim(U \cap W)$. [Hint: if B is a basis of $U \cap W$, let (by Theorem 3) C and D be bases of U and W respectively each containing B . Show that $C \cup D$ is a basis of $U + W$.]

Page 453

Question #6(a):

(a) $V = \mathbb{P}_2$, $\mathbf{v} = x^2 - 3x + 4$, $B = \{x + 2, x^2 - 1, 1\}$.

Page 454

Question #16:

16. Let $V \xrightarrow{T} W \xrightarrow{S} V$ be linear transformations such that $S \circ T = 1_V$. If $\dim V = \dim W$ is finite, show that also $T \circ S = 1_W$ (so T is an isomorphism and $S = T^{-1}$).

Page 466

Exercises, Question #1(h):

(h) If \mathbf{v} is an eigenvector of T and \mathbf{w} is in $\ker T$, then $\mathbf{v} + \mathbf{w}$ is an eigenvector of T .

Page 482

Exercises, Question #1(f):

(f) If T is an isomorphism, the only T -invariant subspaces of V are V and $\{\mathbf{0}\}$.

Page 483

Question #8(b):

(b) Show that λ exists such that $T(\mathbf{v}) = \lambda\mathbf{v}$ for every vector \mathbf{v} in V .

Page 483

Question #14:

14. Let $T : V \rightarrow V$ be a linear operator where $\dim V = n$.
- (a) Show that $E_\lambda(T) \cap E_\mu(T) = \{0\}$ if $\lambda \neq \mu$.
 - (b) If $\lambda \neq \mu$ are the only eigenvalues of an operator T , and if $\dim(E_\lambda(T)) + \dim(E_\mu(T)) = n$, show that T is diagonalizable.
 - (c) If $\lambda \neq \mu$ are the only eigenvalues of T and $\dim V = 2$, show that T is diagonalizable.
 - (d) Give an example where T has exactly two distinct eigenvalues but is not diagonalizable.

Page 495

Example 13, Line 6:

$$\mathbf{e}_m = \mathbf{b}_m - \frac{\langle \mathbf{b}_m, \mathbf{e}_0 \rangle}{\|\mathbf{e}_0\|^2} \mathbf{e}_0 - \frac{\langle \mathbf{b}_m, \mathbf{e}_1 \rangle}{\|\mathbf{e}_1\|^2} \mathbf{e}_1 - \dots - \frac{\langle \mathbf{b}_m, \mathbf{e}_{m-1} \rangle}{\|\mathbf{e}_{m-1}\|^2} \mathbf{e}_{m-1}.$$

Page 503

Question #19:

19. Let $W_1 \subseteq W_2 \subseteq \dots$ be nonzero subspaces of an inner product space V such that $W_m \neq W_{m+1}$ for each m . Choose $\mathbf{b}_1 \neq \mathbf{0}$ in W_1 and, for $m \geq 2$, choose \mathbf{b}_m in W_m but not in W_{m-1} . Show that $\{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3, \dots\}$ is an infinite independent set.

Page 515

Question #8(a):

8. (a) Basic algebraic manipulations give

$$A = \frac{1}{2} \left(\begin{bmatrix} 1 & 4 \\ 0 & 7 \\ -2 & 3 \end{bmatrix} + \begin{bmatrix} 2 & 0 \\ -3 & 4 \\ 0 & 8 \end{bmatrix} \right) = \begin{bmatrix} \frac{3}{2} & 2 \\ -\frac{3}{2} & \frac{11}{2} \\ -1 & \frac{11}{2} \end{bmatrix}.$$

Page 533

2.3 Diagonalization and Eigenvalues

Question #5, Line 3:

parameter family $t \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ if $c \neq 0$. So A is not diagonalizable by Theorem 5.

Page 538

Question #4:

4. These are very interesting recurrences where complex numbers are used to (diagonalize the matrix and) compute a recurrence of ordinary integers. For (b), we obtained the formula (with 2 decimals approximation)

$$\begin{aligned} V_k \approx & (0.11)(-0.69)^k \begin{bmatrix} 2.06 \\ -1.43 \\ 1 \end{bmatrix} \\ & + (0.44 + 1.03i)(1.34 + 1.02i)^k \begin{bmatrix} 0.09 + 0.33i \\ 0.46 + 0.35i \\ 1 \end{bmatrix} \\ & + (0.44 - 1.03i)(1.34 - 1.02i)^k \begin{bmatrix} 0.09 - 0.33i \\ 0.46 - 0.35i \\ 1 \end{bmatrix} \end{aligned}$$

Page 550

Question #19:

19. For (a), $T(\vec{v})$ is already projected, so doing it again won't do anything. For (b), multiply the matrices from Theorem 1.
[ILAW: Exploration 3.5.4.]

Page 555

4.3 Dimension

Question #3(c):

(c) This set has 3 vectors in \mathbb{R}^3 , and they are independent. Hence they form a basis of \mathbb{R}^3 .

Page 559

4.5 Orthogonality

Question #6(b):

(b) The coefficients are $\frac{-4a+b+5c}{42}$, $\frac{-a+b-c}{3}$, $\frac{2a+3b+c}{14}$.

Page 561

Question #8(b):

(b) $U^\perp = \text{span}\{[5 \ 3 \ 1 \ 0], [-5 \ -2 \ 0 \ 1]\}$.

Page 563

Question #5(d):

$$(d) P = \frac{1}{\sqrt{182}} \begin{bmatrix} 3\sqrt{13} & 2\sqrt{14} & 3 \\ -\sqrt{13} & 0 & 13 \\ 2\sqrt{13} & -3\sqrt{14} & 2 \end{bmatrix}$$

Page 567

4.10 Complex Matrices, Question #2(c)

(c) $\|Z\| = 2\sqrt{5}$, $\|W\| = 2\sqrt{2}$; not orthogonal as $\langle Z, W \rangle = 4 + 5i$ is nonzero.

Page 571**Question #4:**

4. The zero vector is $[0, -1]$, and the negative of $[x \ y]$ is $[-x \ -2 \ -y]$.

Axiom S3 is verified as follows:

$$\begin{aligned} a \cdot [x \ y] + b \cdot [x \ y] &= [ax, ay + a - 1] + [bx, by + b - 1] \\ &= [ax + bx, (ay + a - 1) + (by + b - 1) + 1] \\ &= [(a + b)x, (a + b)y + (a + b) - 1] \\ &= (a + b) \cdot [x \ y]. \end{aligned}$$

Page 577**5.6 Invariant Subspaces, Question #2:**

2. Show that $T^2 = T$ by showing that $T^2(\mathbf{b}_i) = T(\mathbf{b}_i)$ for each i . $B_0 = \{\mathbf{b}_1, \mathbf{b}_2 + 2\mathbf{b}_4\}$.

Page 578**Question #17:**

17. We have $U = \text{span}\{\mathbf{v}, T(\mathbf{v}), T^2(\mathbf{v}), \dots, T^{m-1}(\mathbf{v})\}$. If \mathbf{w} is one of these generators of U , it is clear that $T(\mathbf{w})$ is in U , except if $\mathbf{w} = T^{m-1}(\mathbf{v})$. For this, use equation (**) preceding Theorem 6.

Page 580**Question #22(b):**

- (b) If $\| \cdot \|$ came from an inner product, there would (by Theorem 2) be a matrix P such that $[x \ y] P \begin{bmatrix} x \\ y \end{bmatrix} = |x| + |y|$ for all x and y . Show that this is impossible by examining various choices for x and y .